

Date: 29.09.20

The Cauchy problem and Wave Equations

On the theory of ordinary differential equations, by the initial-value problem we mean the problem of finding the solution of a given differential equation with the appropriate number of initial conditions prescribed at an initial point. For example, the second-order ordinary differential equation

$$\frac{d^2 u}{dt^2} = f(t, u, \frac{du}{dt})$$

and the initial conditions

$$u(t_0) = \alpha, \left(\frac{du}{dt}\right)(t_0) = \beta$$

constitute an initial-value problem.

An analogous problem can be defined in the case of partial differential equations. Here we shall state the problem involving second-order partial differential equations in two independent variables. We consider a second-order partial differential equation for the function u in the independent variables x and y and suppose that this equation can be solved explicitly for u_{yy} , and hence, can be represented in the form

$$u_{yy} = f(x, y, u, u_x, u_y, u_{xx}, u_{xy}) \rightarrow (1)$$

For some value $y = y_0$, we prescribe the initial values of the unknown function and of the derivative with respect to y , $u(x, y_0) = f(x)$, $u_y(x, y_0) = g(x)$. $\rightarrow (2)$

The problem of determining the solution of equation (1) satisfying the initial conditions (2) is known as the initial-value problem. For example, the initial-value problem of a ~~semi~~ vibrating string is the problem of finding the solution of the wave equation

$$u_{tt} = c^2 u_{xx}$$

Satisfying the initial conditions

$$u(x, t_0) = u_0(x), \quad u_t(x, t_0) = v_0(x)$$

where $u_0(x)$ is the initial displacement and $v_0(x)$ is the initial velocity.

In the initial-value problems, the initial values usually refer to the data assigned at $y = y_0$. It is not essential that these values be given along the line $y = y_0$, they may very well be prescribed along some curve L_0 in the xy plane. In such a context, the problem is called the Cauchy problem instead of initial-value problem, although the two names are actually synonymous.

▣ we consider the Euler equation

$$A u_{xx} + B u_{xy} + C u_{yy} = F(x, y, u, u_x, u_y) \rightarrow (3)$$

where A, B, C are functions of x and y . Let (x_0, y_0) denote points on a smooth curve L_0 in the xy plane. Also let the parametric equations of this curve L_0 be $x_0 = x_0(\eta), y_0 = y_0(\eta) \rightarrow (4)$ where η is a parameter.

We suppose that two functions $f(\eta)$ and $g(\eta)$ are prescribed along the curve L_0 . The Cauchy problem is now one of determining the solution $u(x, y)$ of equation (3) in the neighborhood of the curve L_0 satisfying the Cauchy conditions

$$u = f(\eta) \quad (5)$$

$$\frac{\partial u}{\partial n} = g(\eta) \quad (6) \rightarrow (7)$$

on the curve L_0 where n is the direction of the normal to L_0 which lies to the left of L_0 in the counterclockwise direction of increasing arc length. The functions $f(\eta)$ and $g(\eta)$ are called Cauchy data.

▣ For every point on L_0 , the value of u is specified by equation (5). Thus, the curve L_0 represented by equation (4) with the condition (5) yields a twisted curve L in (x, y, u) space whose projection on the xy plane is the curve L_0 . Thus, the solution of the Cauchy problem is a surface called an integral surface, in the (x, y, u) space passing through L and satisfying

the condition (5) (ii) which represent a tangent plane to the integral surface along L .

If the function $f(x, y, z)$ is differentiable, then along the curve L_0 , we have

$$\frac{du}{dt} = \frac{\partial u}{\partial x} \frac{dx}{dt} + \frac{\partial u}{\partial y} \frac{dy}{dt} = \frac{df}{dt} \rightarrow (6)$$

$$\text{and } \frac{\partial u}{\partial n} = \frac{\partial u}{\partial x} \frac{dx}{dn} + \frac{\partial u}{\partial y} \frac{dy}{dn} = g \rightarrow (7)$$

$$\text{but } \frac{dx}{dn} = -\frac{dy}{dt} \text{ and } \frac{dy}{dn} = \frac{dx}{dt} \rightarrow (8)$$

The eqn (7) may be written as

$$\frac{\partial u}{\partial n} = -\frac{\partial u}{\partial x} \frac{dy}{dt} + \frac{\partial u}{\partial y} \frac{dx}{dt} = g \rightarrow (9)$$

$$\text{since } \begin{vmatrix} \frac{dx}{dt} & \frac{dy}{dt} \\ -\frac{dy}{dt} & \frac{dx}{dt} \end{vmatrix} = \frac{dx}{dt} \cdot \frac{dx}{dt} + \frac{dy}{dt} \cdot \frac{dy}{dt} \neq 0 \rightarrow (10)$$

It is possible to find u_x and u_y on L_0 from the system of equation (6) and (9).

Since u_x and u_y are known on L_0 , we find the higher derivatives by first differentiating u_x and u_y with respect to t . Thus, we have

$$\frac{\partial u}{\partial x^2} \frac{dx}{dt} + \frac{\partial^2 u}{\partial x \partial y} \frac{dy}{dt} = \frac{d}{dt} \left(\frac{\partial u}{\partial x} \right) \rightarrow (11)$$

$$\frac{\partial^2 u}{\partial x \partial y} \frac{dx}{dt} + \frac{\partial^2 u}{\partial y^2} \frac{dy}{dt} = \frac{d}{dt} \left(\frac{\partial u}{\partial y} \right) \rightarrow (12)$$

From eqn (3)

$$A \frac{\partial^2 u}{\partial x^2} + B \frac{\partial^2 u}{\partial x \partial y} + C \frac{\partial^2 u}{\partial y^2} = F$$

where F is known since u_x and u_y have been found. The system of equations can be solved by u_{xx} , u_{xy} and u_{yy} if

$$\begin{vmatrix} \frac{dx}{dt} & \frac{dy}{dt} & 0 \\ 0 & \frac{dx}{dt} & \frac{dy}{dt} \\ A & B & C \end{vmatrix} \neq 0$$

The eqn $A \left(\frac{dy}{dx} \right)^2 - B \left(\frac{dy}{dx} \right) + C = 0$

is called the characteristic equation. It is then evident that the necessary condition for obtaining the second derivatives is that the curve C_0 must not be a characteristic curve.
